

A CHARACTERIZATION OF E -COMPLETENESS IN VECTOR METRIC SPACES WITH AN APPLICATION IN FIXED POINT THEORY

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ABSTRACT. The main purpose of this article is to introduce the notion of d_v -point in a vector metric space which is a generalization of the notion of d -point in metric spaces and extend Weston's characterization of metric completeness to vector metric spaces in terms of d_v -point. In fact, we have utilized the concepts of lower semicontinuity and uniform continuity in this new framework to establish the main result. Finally, we established relations among minimal points, d_v -points and fixed points in this new setting. As an application of this study, we obtained the analogue of Banach Contraction Principle in vector metric spaces.

Keywords: d_v -point, E -completeness, minimal point, fixed point.

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1. INTRODUCTION

Metric completeness is closely related to metric fixed point theory. Several authors successfully characterized metric completeness in terms of fixed point theory (see [11, 12, 13, 14, 16, 18, 19]). There are a lot of generalizations of the concept of metric spaces such as b -metric space, introduced by Bakhtin [3], partial metric space by Matthews [9], and dislocated metric space by Hitzler et al. [8]. Recently, Xu et al. [21] introduced a kind of new convergence for sequences and a new kind of completeness in cone b -metric spaces over Banach algebras and established a common fixed point theorem for such spaces. Afterwards, Y. Han and others [7], introduced several b -generalized contractive mappings in cone b -metric spaces over Banach algebras and obtained some important fixed point theorems for asymptotically regular mappings by weakening the completeness of the spaces. In 2009, Ćević et al. [5] introduced the concept of vector metric spaces as a generalization of metric spaces, where the metric is Riesz space valued and studied some properties

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of such spaces. In [17], the authors discussed Reich-Perov-type contractive mappings using a novel concept in vector valued metric spaces and gave sufficient conditions for the existence of fixed points for such contractive mappings. Very recently, Çevik et al. [6] proved some coupled fixed point theorems for the functions having mixed monotone properties on ordered vector metric spaces. In 1977, J. D. Weston [20] had characterized metric completeness by means of d -point for lower semicontinuous functions. In this study, our main purpose is to introduce the concept of d_v -point in vector metric spaces and extend Weston's characterization [20] in such spaces in terms of d_v -point. Finally, we apply this new characterization to obtain some important fixed point results in E -complete vector metric spaces.

2. SOME BASIC CONCEPTS

In this section, we recall some basic facts about Riesz spaces mostly of which can be found in [2, 5].

A partially ordered set (X, \preceq) is called a lattice if each pair of elements $x, y \in X$ has a supremum and an infimum.

A real vector space E with an order relation \preceq on E that is compatible with the algebraic structure of E in the sense that satisfies properties:

- (1) $x \preceq y$ implies $x + z \preceq y + z$ for each $z \in E, x, y \in E$;
- (2) $x \preceq y$ implies $tx \preceq ty$ for each $t > 0, x, y \in E$

is called an ordered vector space.

An ordered vector space that is also a lattice is called a Riesz space or vector lattice. Throughout this paper, we take θ as the zero vector of the vector space E . We shall write $x \prec y$ (equivalently, $y \succ x$) if $x \preceq y$ and $x \neq y$. Let E be a Riesz space with the positive cone $E_+ = \{x \in E : \theta \preceq x\}$. If (a_n) is a decreasing sequence in E such that $\inf a_n = a$, we write $a_n \downarrow a$. Similarly, if (a_n) is an increasing sequence in E such that $\sup a_n = a$, we write $a_n \uparrow a$.

Some basic properties of decreasing sequences can be stated as follows:

- (i) $a_n \downarrow a$ and $b_n \downarrow b \Rightarrow a_n + b_n \downarrow a + b$;
- (ii) $a_n \downarrow a \Rightarrow \lambda a_n \downarrow \lambda a$ for $\lambda > 0$ and $\lambda a_n \uparrow \lambda a$ for $\lambda < 0$;
- (iii) $a_n \downarrow a$ and $b_n \downarrow b \Rightarrow a_n \vee b_n \downarrow a \vee b$ and $a_n \wedge b_n \downarrow a \wedge b$, where $a \vee b = \sup\{a, b\}$ and $a \wedge b = \inf\{a, b\}$.

The Riesz space E is said to be Archimedean if $\frac{1}{n}a \downarrow \theta$ holds for every $a \in E_+$.

A Riesz space E is called order complete or Dedekind complete if every nonempty subset of E which is bounded from above (below) has a supremum (infimum). Any order complete Riesz space is Archimedean but the converse is not true, in general.

A sequence (b_n) in E is called order convergent or o-convergent to b if there exists a sequence (a_n) in E satisfying $a_n \downarrow \theta$ and $|b_n - b| \preceq a_n$ for all n , and written $b_n \xrightarrow{o} b$ or $o - \lim b_n = b$, where $|a| = \sup\{a, -a\}$ for any $a \in E$. Moreover, (b_n) is called order-Cauchy or o-Cauchy if there exists a sequence (a_n) in E such that $a_n \downarrow \theta$ and $|b_n - b_{n+p}| \preceq a_n$ holds for all n and p . E is called o-complete if every o-Cauchy sequence is o-convergent. For other notations and facts about Riesz spaces, we refer to [1].

Lemma 2.1. [2] *If E is a Riesz space and $a \preceq ka$ where $a \in E_+$ and $k \in [0, 1)$, then $a = \theta$.*

Definition 2.1. A Riesz space E is called regular if every decreasing sequence in E which is bounded from below is o -convergent.

Remark 2.1. If E is Dedekind complete and totally ordered, then as a consequence it follows that E is regular.

Definition 2.2. [5] Let X be a nonempty set and E be a Riesz space. The function $d_v : X \times X \rightarrow E$ is said to be a vector metric (or E -metric) if it satisfies the following properties:

- (v₁) $d_v(x, y) = \theta$ if and only if $x = y$;
- (v₂) $d_v(x, y) \preceq d_v(x, z) + d_v(y, z)$ for all $x, y, z \in X$.

The triple (X, d_v, E) is said to be a vector metric space.

It is easy to observe that vector metric spaces generalize metric spaces.

In a vector metric space (X, d_v, E) , the following assertions hold:

- (i) $\theta \preceq d_v(x, y)$ for all $x, y \in X$;
- (ii) $d_v(x, y) = d_v(y, x)$ for all $x, y \in X$;
- (iii) $|d_v(x, z) - d_v(y, z)| \preceq d_v(x, y)$ for all $x, y, z \in X$;
- (iv) $|d_v(x, z) - d_v(y, w)| \preceq d_v(x, y) + d_v(z, w)$ for all $x, y, z, w \in X$.

Example 2.1. [5] A Riesz space E is a vector metric space with $d_v : E \times E \rightarrow E$ defined by

$$d_v(x, y) = |x - y|.$$

This vector metric is said to be absolute valued metric on E .

Example 2.2. [5] It is well known that \mathbb{R}^2 is a Riesz space with coordinate wise ordering defined by

$$(x_1, y_1) \preceq (x_2, y_2) \text{ if and only if } x_1 \leq x_2 \text{ and } y_1 \leq y_2$$

for $(x_1, y_1), (x_2, y_2) \in \mathbb{R}^2$.

Again, \mathbb{R}^2 is a Riesz space with lexicographical ordering defined by

$$(x_1, y_1) \preceq (x_2, y_2) \text{ if and only if } x_1 < x_2 \text{ or } x_1 = x_2, y_1 \leq y_2.$$

It is worth noting that \mathbb{R}^2 is Archimedean with coordinate wise ordering but not with lexicographical ordering.

Then, $d_v : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by

$$d_v((x_1, y_1), (x_2, y_2)) = (\alpha |x_1 - x_2|, \beta |y_1 - y_2|)$$

is a vector metric, where α, β are positive real numbers.

Example 2.3. [5] Let $d_v : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}^2$ be defined by

$$d_v(x, y) = (\alpha |x - y|, \beta |x - y|)$$

where $\alpha, \beta \geq 0$ and $\alpha + \beta > 0$. Then d_v is a vector metric with coordinate wise or lexicographical ordering.

Example 2.4. Let $C[a, b]$ be the space of all real valued continuous functions defined on $[a, b]$. For $f, g \in C[a, b]$, we define $f \preceq g$ if and only if $f(x) \leq g(x)$ for all $x \in [a, b]$. Then $C[a, b]$ is a Riesz space. For a fixed $f \in C[a, b]$, where $f(x) > 0$ for all x , we define $d_v : \mathbb{R} \times \mathbb{R} \rightarrow C[a, b]$ by

$$d_v(x, y) = |x - y| f.$$

Then d_v is a vector metric.

Definition 2.3. [5] Let (X, d_v, E) be a vector metric space and let (x_n) be a sequence in X . Then

- (i) (x_n) vectorially converges or E -converges to a point $x \in X$, written $x_n \xrightarrow{d_v, E} x$, if there is a sequence (a_n) in E satisfying $a_n \downarrow \theta$ and $d_v(x_n, x) \preceq a_n$ for all n .
- (ii) (x_n) is called vectorially Cauchy or E -Cauchy, if there is a sequence (a_n) in E such that $a_n \downarrow \theta$ and $d_v(x_n, x_{n+p}) \preceq a_n$ holds for all n and p .
- (iii) (X, d_v, E) is said to be E -complete if each E -Cauchy sequence in X E -converges to a point in X .
- (iv) A subset Y in (X, d_v, E) is said to be E -closed whenever $(x_n) \subseteq Y$ and $x_n \xrightarrow{d_v, E} x$ imply $x \in Y$.

Remark 2.2. It is easy to observe that there is a relationship between E -convergence on X with the o -convergence on E . In fact, $x_n \xrightarrow{d_v, E} x$ if and only if $d(x_n, x) \overset{o}{\rightarrow} \theta$.

Remark 2.3. If $E = \mathbb{R}$, then the notion of E -convergence coincides with the notion of metric convergence. Similarly, the concept of E -Cauchy sequence coincides with the concept of metric Cauchy sequence.

Remark 2.4. If $X = E$ and d_v is the absolute valued vector metric on X , then the concept of vectorially convergence coincides with the concept of order convergence.

Lemma 2.2. [5] Let (X, d_v, E) be a vector metric space and let $x_n \xrightarrow{d_v, E} x$. Then, we have the following properties:

- (i) The limit x is unique.
- (ii) Every subsequence of (x_n) E -converges to x .
- (iii) If also $y_n \xrightarrow{d_v, E} y$, then $d_v(x_n, y_n) \overset{o}{\rightarrow} d_v(x, y)$.

Definition 2.4. Let E be Dedekind complete and let (X, d_v, E) be a vector metric space. A function $\varphi : X \rightarrow E$ which is bounded from below is called a lower semicontinuous function on X whenever

$$x_n \xrightarrow{d_v, E} x \implies \varphi(x) \preceq \liminf_{n \rightarrow \infty} \varphi(x_n) := \sup_{n \geq 1} \inf_{m \geq n} \varphi(x_m).$$

Definition 2.5. Let (X, d_v, E) be a vector metric space and $f : X \rightarrow E$. Then, the function f is called uniformly continuous on X if for any $\epsilon \succ \theta$ there is a $c \in E$ with $c \succ \theta$ such that

$$d_v(x, y) \prec c \implies |f(x) - f(y)| \prec \epsilon.$$

3. MAIN RESULTS

We begin with a definition.

Definition 3.1. Let (X, d_v, E) be a vector metric space and $h : X \rightarrow E$. A point $x_0 \in X$ is called a d_v -point for h if for every other point $x \in X$ with $h(x_0) - h(x) \succ \theta$,

$$h(x_0) - h(x) \prec d_v(x_0, x).$$

Example 3.1. Let $E = \mathbb{R}^2$, $X = [0, \infty)$ and $d_v : X \times X \rightarrow E$ be defined by

$$d_v(x, y) = (|x - y|, |x - y|).$$

Then (X, d_v, E) is a vector metric space with coordinate wise ordering.

We define $h : X \rightarrow E$ by

$$h(x) = \left(-\frac{x}{2}, -\frac{x}{2}\right) \text{ for all } x \in X.$$

Then,

$$h(0) - h(x) = (0, 0) - \left(-\frac{x}{2}, -\frac{x}{2}\right) = \left(\frac{x}{2}, \frac{x}{2}\right) \prec d_v(0, x)$$

for every $x \in X$ with $x \neq 0$. Also, $h(0) - h(x) \succ \theta$. Thus, 0 is a d_v -point for h .

Theorem 3.1. Let E be a Riesz space which is Dedekind complete and totally ordered. Let (X, d_v, E) be an E -complete vector metric space. Then any lower semicontinuous function $h : X \rightarrow E$ has a d_v -point. If (X, d_v, E) is not E -complete but E is o -complete and E_+ is closed w.r.t. absolute valued vector metric on E , then there is a uniformly continuous function $g : X \rightarrow E$ which is bounded below but has no d_v -point.

Proof. For any point $x_1 \in X$, we construct a sequence (x_n) in the following way: For each $n \in \mathbb{N}$, let

$$\alpha(x_n) = \inf\{h(x) : h(x_n) - h(x) \succeq d_v(x_n, x) \succ \theta\} = \inf A,$$

where $A = \{h(x) : h(x_n) - h(x) \succeq d_v(x_n, x) \succ \theta\}$.

Since h is bounded below and E is Dedekind complete, it follows that $\alpha(x_n)$ exists.

Let x_{n+1} be a point in X such that

$$h(x_n) - h(x_{n+1}) \succeq d_v(x_n, x_{n+1}) \succ \theta \tag{1}$$

and

$$h(x_{n+1}) \prec \alpha(x_n) + \frac{c_0}{n}, \tag{2}$$

where $c_0 \succ \theta$ is a fixed element of E .

In fact, if $\alpha(x_n) + \frac{c_0}{n} \preceq h(x)$ for all $h(x) \in A$, and this is possible since E is totally ordered, then $\alpha(x_n) + \frac{c_0}{n}$ becomes a lower bound of A satisfying $\alpha(x_n) \prec \alpha(x_n) + \frac{c_0}{n}$ which contradicts the fact that $\alpha(x_n) = \inf A$. The preceding discussion ensures the existence of $x_{n+1} \in X$ satisfying conditions (1) and (2).

It is worthy to note that in above construction, we have considered none of x_n as a d_v -point for h . Because, if x_n is a d_v point for h , then we have nothing to prove.

Condition (1) guarantees that the sequence $(h(x_n))$ is nonincreasing in E . As h is bounded below, it follows that the sequence $(h(x_n))$ is also bounded below. Since E is Dedekind complete and totally ordered, it is also regular. So, we obtain that the sequence $(h(x_n))$ is o -convergent and hence it is o -Cauchy. So, there exists a sequence (a_n) in E such that $a_n \downarrow \theta$ and $|h(x_n) - h(x_{n+p})| \preceq a_n$ holds for all n and p .

For $m \geq n$, we have

$$\begin{aligned} h(x_n) - h(x_m) &= h(x_n) - h(x_{n+1}) + h(x_{n+1}) - h(x_{n+2}) \\ &\quad + \cdots + h(x_{m-1}) - h(x_m) \\ &\succeq d_v(x_n, x_{n+1}) + d_v(x_{n+1}, x_{n+2}) + \cdots + d_v(x_{m-1}, x_m) \\ &\succeq d_v(x_n, x_m). \end{aligned} \tag{3}$$

Hence,

$$d_v(x_n, x_m) \preceq h(x_n) - h(x_m) \preceq |h(x_n) - h(x_m)|.$$

Taking $p = m - n$, we get

$$d_v(x_n, x_{n+p}) \preceq |h(x_n) - h(x_{n+p})| \preceq a_n, \quad \forall n, p.$$

This proves that the sequence (x_n) is E -Cauchy in X . The E -completeness of X implies that the sequence (x_n) is E -convergent to some point in X , say x_0 , that is, $x_n \xrightarrow{d_v, E} x_0$.

From (3), it follows that

$$h(x_m) \preceq h(x_n) - d_v(x_n, x_m) \tag{4}$$

for all $m \geq n$. In view of condition (4), Lemma 2.2 and lower semicontinuity of the function h , one can compute that

$$\begin{aligned} h(x_0) &\preceq \liminf_{m \rightarrow \infty} h(x_m) \\ &\preceq \liminf_{m \rightarrow \infty} [h(x_n) - d_v(x_n, x_m)] \\ &= h(x_n) - d_v(x_n, x_0) \end{aligned}$$

for all $n \geq 1$. Thus,

$$h(x_n) - h(x_0) \succeq d_v(x_n, x_0) \tag{5}$$

for all $n \geq 1$.

If x_0 is not a d_v -point for h , then for some $x (\neq x_0) \in X$,

$$h(x_0) - h(x) \succeq d_v(x_0, x) \succ \theta. \tag{6}$$

Using (5) and (2), we obtain

$$h(x) \preceq h(x_{n+1}) + h(x) - h(x_0) \prec \alpha(x_n) + \frac{c_0}{n} + h(x) - h(x_0). \tag{7}$$

Since $c_0 \succ \theta$ and $h(x_0) - h(x) \succ \theta$, we claim that there exists $n \in \mathbb{N}$ such that

$$\frac{c_0}{n} \prec h(x_0) - h(x).$$

In fact, if $h(x_0) - h(x) \preceq \frac{c_0}{n}$ for all $n \in \mathbb{N}$, then $h(x_0) - h(x)$ becomes a lower bound the sequence $(\frac{c_0}{n})$. Therefore, $h(x_0) - h(x) \preceq \inf \frac{c_0}{n}$. Since E is Dedekind complete, it is also Archimedean and so $\frac{c_0}{n} \downarrow \theta$. Thus, we obtain that $h(x_0) - h(x) \preceq \theta$, a contradiction and our claim is justified.

Our preceding discussion implies that $\alpha(x_n) + \frac{c_0}{n} + h(x) - h(x_0) \prec \alpha(x_n)$. Thus, condition (7) assures that $h(x) \prec \alpha(x_n)$.

From conditions (5) and (6), we obtain that

$$\begin{aligned} h(x_n) - h(x) &= h(x_n) - h(x_0) + h(x_0) - h(x) \\ &\succeq d_v(x_n, x_0) + d_v(x_0, x) \\ &\succ \theta \end{aligned}$$

which implies that $h(x_n) \succ h(x)$. So, $x_n \neq x$ and therefore $d_v(x_n, x) \succ \theta$.

Moreover,

$$h(x_n) - h(x) \succeq d_v(x_n, x_0) + d_v(x_0, x) \succeq d_v(x_n, x) \succ \theta.$$

The definition of $\alpha(x_n)$ ensures that $h(x) \succeq \alpha(x_n)$ which contradicts the fact that $h(x) \prec \alpha(x_n)$. Thus, x_0 is a d_v -point for h .

For the last part, we suppose that (X, d_v, E) is not E -complete but E is o -complete. Then there exists an E -Cauchy sequence (x_n) in X which is not E -convergent. We now compute that for any $x \in X$, the sequence $(2d_v(x, x_n))$ is o -Cauchy in E .

For $x \in X$, we have

$$d_v(x, x_n) \preceq d_v(x, x_m) + d_v(x_m, x_n)$$

which implies that

$$d_v(x, x_n) - d_v(x, x_m) \preceq d_v(x_m, x_n). \quad (8)$$

Interchanging n and m , we obtain

$$d_v(x, x_m) - d_v(x, x_n) \preceq d_v(x_m, x_n). \quad (9)$$

Conditions (8) and (9) together imply that

$$|d_v(x, x_n) - d_v(x, x_m)| \preceq d_v(x_m, x_n) \text{ for all } m, n \in \mathbb{N}. \quad (10)$$

Suppose that $m > n$ and we put $p = m - n$. Then condition (10) reduces to

$$|d_v(x, x_n) - d_v(x, x_{n+p})| \preceq d_v(x_n, x_{n+p}) \text{ for all } n, p. \quad (11)$$

As (x_n) is E -Cauchy, it follows from (11) that the sequence $(2d_v(x, x_n))$ is o -Cauchy in E and hence it is o -convergent, E being o -complete. Let $g(x) \in E$ be its limit. Since $2d_v(x, x_n) \in E_+$ and E_+ being closed w.r.t. absolute valued vector metric on E , it follows that $g(x) \in E_+$. Clearly, $g(x) \succ \theta$. In fact, if $g(x) = \theta$, then there is a sequence (a_n) in E satisfying $a_n \downarrow \theta$ and $|2d_v(x_n, x) - \theta| \preceq a_n$ for all n . This gives that,

$$2d_v(x_n, x) \preceq |2d_v(x_n, x) - \theta| \preceq a_n \text{ for all } n.$$

Thus, the sequence (x_n) becomes E -convergent which contradicts our assumed hypothesis. Therefore, we obtained that the function g is bounded below.

If $x_0 \in X$, then $g(x_0) = o - \lim 2d_v(x_0, x_n)$. Also, $g(x) = o - \lim 2d_v(x, x_n)$. Then, there are sequences (a_n) , (b_n) in E satisfying $a_n \downarrow \theta$, $b_n \downarrow \theta$ such that

$$|2d_v(x_n, x_0) - g(x_0)| \preceq a_n \text{ and } |2d_v(x_n, x) - g(x)| \preceq b_n \text{ for all } n. \quad (12)$$

Now,

$$\begin{aligned} |2d_v(x_n, x_0) - 2d_v(x_n, x) - (g(x_0) - g(x))| &\preceq |2d_v(x_n, x_0) - g(x_0)| \\ &\quad + |2d_v(x_n, x) - g(x)| \\ &\preceq (a_n + b_n) \text{ for all } n, \end{aligned}$$

where $(a_n + b_n) \downarrow \theta$. This proves that

$$g(x_0) - g(x) = o - \lim [2d_v(x_n, x_0) - 2d_v(x_n, x)] \preceq 2d_v(x_0, x). \quad (13)$$

Interchanging x_0 and x , we obtain

$$g(x) - g(x_0) \preceq 2d(x_0, x). \quad (14)$$

Conditions (13) and (14) together imply that

$$|g(x_0) - g(x)| \preceq 2d(x_0, x).$$

Let $\epsilon \succ \theta$ be given. We choose $c = \frac{\epsilon}{2} \succ \theta$. Then,

$$|g(x_0) - g(x)| \prec \epsilon \text{ whenever } d(x_0, x) \prec c.$$

This proves that g is uniformly continuous.

By an argument similar to that used above, we can compute that

$$g(x_0) + g(x) = o - \lim[2d_v(x_n, x_0) + 2d_v(x_n, x)] \succeq 2d_v(x_0, x).$$

This gives that

$$\frac{1}{2}[g(x_0) + g(x)] \succeq d_v(x_0, x).$$

Now,

$$\begin{aligned} g(x_0) - g(x) &= \frac{1}{2}[g(x_0) + g(x)] + \frac{1}{2}[g(x_0) - 3g(x)] \\ &\succeq d_v(x_0, x) + \frac{1}{2}[g(x_0) - 3g(x)]. \end{aligned} \tag{15}$$

If $g(x_0) - g(x) \succ \theta$, then $g(x) \prec g(x_0)$. Again, $g(x) \succ \theta$. So, it must be the case that $\theta \prec g(x_0)$.

It now follows from condition (12) that

$$|2d_v(x_n, x) - g(x)| \preceq b_n \text{ for all } n.$$

This ensures that

$$g(x) - 2d_v(x_n, x) \preceq |2d_v(x_n, x) - g(x)| \preceq b_n \text{ for all } n.$$

This being true for any $x \in X$, we have

$$g(x_{n+p}) \preceq b_n + 2d_v(x_n, x_{n+p}) \text{ for all } n \text{ and } p. \tag{16}$$

The sequence (x_n) being E -Cauchy, there is a sequence (ζ_n) in E satisfying $\zeta_n \downarrow \theta$ such that

$$d_v(x_n, x_{n+p}) \preceq \zeta_n \text{ for all } n \text{ and } p.$$

Therefore, we obtain from condition (16) that

$$3g(x_{n+p}) \preceq 3(b_n + 2\zeta_n) = c_n \text{ for all } n \text{ and } p, \tag{17}$$

where $c_n = 3(b_n + 2\zeta_n) \downarrow \theta$.

We now claim that there exists an $n_0 \in \mathbb{N}$ such that $c_{n_0} \prec g(x_0)$. If possible, suppose that $c_n \succeq g(x_0)$ for all n . Then, $\inf c_n \succeq g(x_0) \succ \theta$, which contradicts the fact that $c_n \downarrow \theta$. Thus, our claim is justified. Since the sequence (c_n) is decreasing, it follows that $c_n \prec g(x_0)$ for all $n \geq n_0$. In view of condition (17), we get

$$3g(x_{n+p}) \prec g(x_0) \text{ for all } n \geq n_0 \text{ and } p.$$

Thus, $g(x_0) - 3g(x) \succ \theta$ if $x = x_{n+p} (\neq x_0)$ and $n \geq n_0$. It now follows from condition (15) that $g(x_0) - g(x) \succ d(x_0, x)$ if $x = x_{n+p}$ and $n \geq n_0$. So, x_0 is not a d_v -point for g . □

The following corollary is the main result of J. D. Weston [20].

Corollary 3.1. *If the metric space (X, d) is complete then any lower semicontinuous function $X \rightarrow \mathbb{R}$ which is bounded below has a d -point. If (X, d) is not complete there is a uniformly continuous function $X \rightarrow \mathbb{R}$ which is bounded below but has no d -point.*

Proof. The result follows from Theorem 3.1 by taking $E = \mathbb{R}$ with usual metric. \square

Remark 3.1. Theorem 3.1 is an extension of the main result of Weston [20] in metric spaces to vector metric spaces.

The following two examples ensure the validity of our main Theorem 3.1.

Example 3.2. Let $E = F_c[0, 1]$ be the space of all real valued constant functions defined on $[0, 1]$. For $f, g \in F_c[0, 1]$, we define $f \preceq g$ if and only if $f(x) \leq g(x)$ for all $x \in [0, 1]$. Then $F_c[0, 1]$ is a Riesz space which is Dedekind complete and totally ordered. Let $X = [0, 1]$ and choose a fixed $T \in F_c[0, 1]$, where $T(x) = k > 0$ for all $x \in [0, 1]$. We define $d_v : X \times X \rightarrow F_c[0, 1]$ by

$$d_v(x, y) = |x - y| T \text{ for all } x, y \in X.$$

Then (X, d_v, E) is an E -complete vector metric space. Let $h : X \rightarrow E$ be defined by $h(x) = -\frac{x}{5}T$ for all $x \in X$. Then, $h(x) = -\frac{x}{5}T \succeq -\frac{1}{5}T$ for all $x \in X$ which ensures that h is bounded from below. Moreover, it is easy to verify that h is a lower semicontinuous function. We now compute that

$$h(0) - h(x) = \frac{x}{5}T = \frac{1}{5}d_v(0, x) \prec d_v(0, x)$$

for every $x \in X$ with $x \neq 0$. Also, $h(0) - h(x) \succ O$, zero function in E for $x \neq 0$. Thus, all the hypotheses of the first part of Theorem 3.1 holds good and we observe that 0 is a d_v -point for h .

Example 3.3. Let $E = \mathbb{R}$ with usual metric. Then \mathbb{R} is Dedekind complete and totally ordered with usual " \leq ". Let $X = (0, 1)$ and $d_v : X \times X \rightarrow E$ be defined by

$$d_v(x, y) = |x - y| \text{ for all } x, y \in X.$$

Then (X, d_v, E) is not an E -complete vector metric space. Let $g : X \rightarrow E$ be defined by $g(x) = 2x$ for all $x \in X$. Clearly, g is uniformly continuous and bounded from below. Thus, we have all the hypotheses of the last part of Theorem 3.1.

We now show that g has no d_v -point. If possible, suppose that $x_0 \in X$ is a d_v -point for g . Then for any $x \in X$, $x \neq x_0$ with $g(x_0) - g(x) > 0$, we have

$$g(x_0) - g(x) < d_v(x_0, x).$$

This implies that,

$$2(x_0 - x) < |x_0 - x|. \quad (18)$$

But, $g(x_0) - g(x) > 0 \Rightarrow x_0 > x$. It now follows from (18) that $2(x_0 - x) < |x_0 - x| = x_0 - x \Rightarrow x_0 < x$, a contradiction. This proves that g has no d_v -point.

4. AN APPLICATION IN FIXED POINT THEORY

In this section we give an application of our main Theorem 3.1 in fixed point theory. We assume that (X, d_v, E) is a vector metric space, E is totally ordered and $h : X \rightarrow E$ is a function.

Remark 4.1. When d_v and h are given, a relation " \ll " can be defined on X as follows:

$$x \ll y \text{ if and only if } h(y) - h(x) \succeq d_v(x, y).$$

This relation orders X . In fact, " \ll " is reflexive, antisymmetric and transitive.

Definition 4.1. A point x_0 in (X, d_v, E) is said to be a minimal point w.r.t. \ll if and only if $x \ll x_0$ implies $x = x_0$.

Theorem 4.1. *A point of X is a d_v -point for h if and only if it is a minimal point w.r.t. \ll .*

Proof. Let $x_0 \in X$ be a d_v -point for h . Then, for every other point $x(\neq x_0) \in X$ with $h(x_0) - h(x) \succ \theta$,

$$h(x_0) - h(x) \prec d_v(x_0, x). \tag{19}$$

Now $x \ll x_0$ implies that $h(x_0) - h(x) \succeq d_v(x, x_0)$. This gives that $x = x_0$. Because if $x \neq x_0$, then $h(x_0) - h(x) \succeq d_v(x, x_0) \succ \theta$. So it follows from condition (19) that $h(x_0) - h(x) \prec d_v(x, x_0)$, which is a contradiction. Therefore, x_0 is a minimal point w.r.t. \ll .

Conversely, let x_0 be a minimal point w.r.t. \ll . Then $x \ll x_0$ implies that $x = x_0$. That is, $x \ll x_0$ does not hold for any $x \in X$ with $x \neq x_0$. As E is totally ordered, we have $h(x_0) - h(x) \prec d_v(x, x_0)$ for all $x \in X$ with $x \neq x_0$. This gives that x_0 is a d_v -point for h . □

Theorem 4.2. *If a function $f : X \rightarrow X$ is such that it may be possible to choose d_v and h so that the relation \ll has the property that $fx \neq x$ implies $fx \ll x$, then any d_v -point for h is a fixed point for f .*

Proof. Let $x_0 \in X$ be a d_v -point for h . Then, for every other point $x(\neq x_0) \in X$ with $h(x_0) - h(x) \succ \theta$,

$$h(x_0) - h(x) \prec d_v(x, x_0). \tag{20}$$

If $fx_0 \neq x_0$, then by hypothesis $fx_0 \ll x_0$ which implies that

$$h(x_0) - h(fx_0) \succeq d_v(fx_0, x_0) \succ \theta,$$

which contradicts the condition (20). So, it must be the case that $fx_0 = x_0$. This shows that x_0 is a fixed point of f . □

We now apply Theorems 3.1 and 4.2 to prove analogue of Banach Contraction Principle in vector metric spaces.

Theorem 4.3. *Suppose that E is a Riesz space which is Dedekind complete and totally ordered. Let (X, d_v, E) be an E -complete vector metric space and let $f : X \rightarrow X$ be a mapping satisfying the following condition:*

$$d_v(fx, fy) \preceq \alpha d_v(x, y) \tag{21}$$

for all $x, y \in X$, where $0 \leq \alpha < 1$ is a constant. Then f has a unique fixed point in X .

Proof. Let $h(x) = \beta d_v(fx, x)$, where $\beta = \frac{1}{1-\alpha} > 0$ and $x \in X$. It is obvious that h is bounded from below. We first show that $h : X \rightarrow E$ is a lower semicontinuous function. Let $y_n \xrightarrow{d_v, E} y$ in (X, d_v, E) . We have to show that

$$h(y) \preceq \liminf_{n \rightarrow \infty} h(y_n).$$

By using condition (21), we have

$$\begin{aligned} h(y) = \beta d_v(fy, y) &\preceq \beta [d_v(fy, y_n) + d_v(y_n, y)] \\ &\preceq \beta [d_v(fy, fy_n) + d_v(fy_n, y_n) + d_v(y_n, y)] \\ &\preceq \beta [\alpha d_v(y, y_n) + d_v(fy_n, y_n) + d_v(y_n, y)] \\ &= \beta(\alpha + 1) d_v(y, y_n) + h(y_n). \end{aligned}$$

This gives that,

$$h(y) \preceq \liminf_{n \rightarrow \infty} h(y_n).$$

Thus, h is a lower semicontinuous function on an E -complete vector metric space (X, d_v, E) . Therefore, Theorem 3.1 ensures the existence of a d_v -point u (say) for h .

We now show that $fx \neq x$ implies $fx \ll x$.

Let $fx \neq x$. By using condition (21), we obtain

$$\begin{aligned} h(x) - h(fx) &= \beta [d_v(fx, x) - d_v(f^2x, fx)] \\ &\succeq \beta [d_v(fx, x) - \alpha d_v(fx, x)] \\ &= \beta (1 - \alpha) d_v(fx, x) \\ &= d_v(fx, x). \end{aligned}$$

Thus f satisfies the condition that $fx \neq x$ implies $fx \ll x$. By applying Theorem 4.2, it follows that the d_v -point u for h is a fixed point for f in X .

For uniqueness, let $v \in X$ be another fixed point of f . Then, by condition (21), we get

$$d_v(u, v) = d_v(fu, fv) \preceq \alpha d_v(u, v).$$

Since $0 \leq \alpha < 1$, it follows from Lemma 2.1 that $d_v(u, v) = \theta$ and hence $u = v$. \square

The following example supports our Theorem 4.3.

Example 4.1. We consider $E = F_c[0, 1]$ as in Example 3.2. Then E is a Riesz space which is Dedekind complete and totally ordered. Let $X = [0, \infty)$ and choose a fixed $T \in E$, where $T(x) = k > 0$ for all $x \in [0, 1]$. We define $d_v : X \times X \rightarrow E$ by

$$d_v(x, y) = |x - y| T \text{ for all } x, y \in X.$$

Then (X, d_v, E) is an E -complete vector metric space. Let $f : X \rightarrow X$ be a mapping defined by $fx = \frac{x+1}{2}$ for all $x \in X$. We now compute that

$$d_v(fx, fy) = |fx - fy| T = \frac{1}{2} |x - y| T = \frac{1}{2} d_v(x, y) \text{ for all } x, y \in X.$$

Thus, all the conditions of Theorem 4.3 holds true and we observe that 1 is the unique fixed point of f in X .

Remark 4.2. It is worthy to note that the well known Banach Contraction Principle [4] in metric spaces can be obtained from Theorem 4.3 by taking $E = \mathbb{R}$.

5. CONCLUSIONS

In this study, we characterized E -completeness in vector metric spaces in terms of d_v -point. As a consequence of this study, we have been able to establish an important fixed point theorem in vector metric spaces. Our main result extends the result of Weston [20].

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